



Health, demographic change and wellbeing
Personalising health and care: Advancing active and healthy ageing
H2020-PHC-19-2014
Research and Innovation Action

ACANTO

A CyberphysicAl social NeTwOrk
 using robot friends 

Deliverable D10.1
Project Presentation Brochure

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Dissemination Level	
PU	Public <input checked="" type="checkbox"/>
CO	Confidential, only for members of the consortium (including the Commission Services)

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Executive Summary

This deliverable contains the advertisement material produced by the ACANTO consortium. The deliverable consists of a flyer that can be printed and distributed in exhibitions and conferences.
The deliverable has been rejected by the EC owing to formal problems in the accompanying cover page. This re-submission solves these problems.

Chapter 1

Brochure Image

The image displaying the brochure is reported in the next pages.

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ACANTO

A Cyberphysical social NetWork
using robot friends

The **ACANTO** project aims to increase the number of older adults who engage in a regular and sustained physical activity.

This result is sought by developing a **robotic friend** that supports the execution of everyday activities that entail a controlled physical effort in public spaces and an intelligent system that produces activity recommendation considering the habit and the preference of the user observed through the robot.

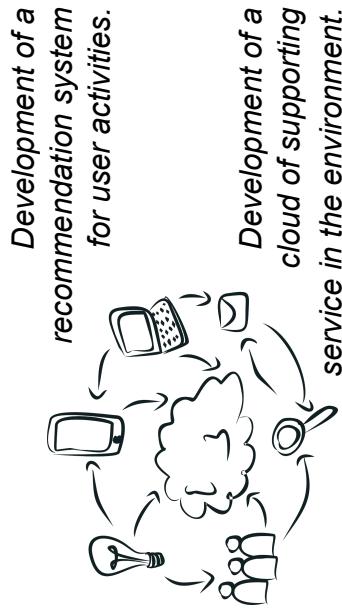
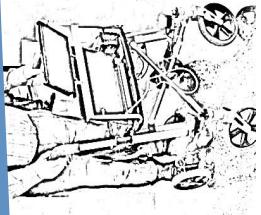
Our long term objectives are a 50% reduction of falls and traumatic events in the adults age class 75+, a reduction of the occurrence and of the impact of chronic diseases and a general **improvement of physical conditions and well-being**.

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OBJECTIVES



Development of a robotic friend (FriWalk) and the audio-visual interfaces (FriTab)



Constant involvement of the different stakeholders



INNOVATION



ACANTO will produce innovation in the following areas:

- a) **Sensing Technologies**
- b) **Interfaces**
- c) **Clinical practise**
- d) **Social Networks for user recommendation**



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